

The Matrix Representation of a Linear Transformation

Def. Let V be a finite dimensional vector space. An **ordered basis for V** is a basis for V with a specific order.

Ex. In \mathbb{R}^3 let $B = \{e_1, e_2, e_3\}$ where $e_1 = \langle 1, 0, 0 \rangle$, $e_2 = \langle 0, 1, 0 \rangle$,
 $e_3 = \langle 0, 0, 1 \rangle$.

B is called the standard ordered basis for \mathbb{R}^3 .

$C = \{e_2, e_1, e_3\}$ is a different ordered basis for \mathbb{R}^3 .

Even though B and C contain the same basis vectors, they appear in different orders in each set.

As we will see shortly, when we express vectors in terms of a basis, the order of the basis matters.

Just as e_1, e_2, \dots, e_n is the standard ordered basis for \mathbb{R}^n , $\{1, x, x^2, \dots, x^n\}$ is the standard ordered basis for $P_n(\mathbb{R})$.

Def. Let $B = \{v_1, v_2, \dots, v_n\}$ be an ordered basis for a finite dimensional vector space V . For $v \in V$, let a_1, \dots, a_n be the unique real numbers such that

$$v = a_1v_1 + \dots + a_nv_n.$$

we define the **coordinate vector of v** relative to B by

$$[v]_B = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix}.$$

Ex. $B = \{v_1, v_2, v_3\} = \{e_1, e_2, e_3\}$ and $B' = \{w_1, w_2, w_3\} = \{e_2, e_1, e_3\}$ are ordered bases for \mathbb{R}^3 . The vector $v = \langle 5, -3, 2 \rangle$ is given by:

$$\begin{aligned}\langle 5, -3, 2 \rangle &= 5e_1 - 3e_2 + 2e_3 \\ &= 5v_1 - 3v_2 + 2v_3.\end{aligned}$$

Thus we have: $[v]_B = \begin{bmatrix} 5 \\ -3 \\ 2 \end{bmatrix}$.

On the other hand:

$$\begin{aligned}\langle 5, -3, 2 \rangle &= 5e_1 - 3e_2 + 2e_3 \\ &= -3w_1 + 5w_2 + 2w_3.\end{aligned}$$

Which gives us: $[v]_{B'} = \begin{bmatrix} -3 \\ 5 \\ 2 \end{bmatrix}$.

Ex. Let $V = P_2(\mathbb{R})$ and $B = \{v_1, v_2, v_3\} = \{1, x, x^2\}$, $B' = \{w_1, w_2, w_3\} = \{x^2, x, 1\}$ ordered bases for V . Then

$f(x) = 3 - 4x + 5x^2$ is represented by:

$$f(x) = 3 - 4x + 5x^2 = 3v_1 - 4v_2 + 5v_3 \quad \Rightarrow \quad [f]_B = \begin{bmatrix} 3 \\ -4 \\ 5 \end{bmatrix}.$$

$$f(x) = 3 - 4x + 5x^2 = 5w_1 - 4w_2 + 3w_3 \quad \Rightarrow \quad [f]_{B'} = \begin{bmatrix} 5 \\ -4 \\ 3 \end{bmatrix}.$$

Let V and W be finite dimensional vector spaces with ordered bases

$B = \{v_1, \dots, v_n\}$ and $C = \{w_1, \dots, w_m\}$ respectively.

Let $T: V \rightarrow W$ be linear.

Then for each j , $1 \leq j \leq n$ there exists a unique set of real numbers $a_{ij} \in \mathbb{R}$, $1 \leq i \leq m$ such that

$$T(v_j) = a_{1j}w_1 + a_{2j}w_2 + \dots + a_{mj}w_m; \quad 1 \leq j \leq n.$$

Def. We call the $m \times n$ matrix A defined by

$$A = \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{bmatrix}$$

the **matrix representation of T in the ordered bases B and C** and write

$$A = [T]_B^C.$$

If $V = W$ and $B = C$ we write $A = [T]_B$.

Notice that the j^{th} column of A is simply $[T(v_j)]_C$:

$$A = [T]_B^C = [T(v_1) \quad T(v_2) \cdots T(v_n)].$$

Ex. Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ be the linear transformation defined by

$$T(\langle a_1, a_2 \rangle) = \langle a_1 - 2a_2, 0, 3a_1 + 2a_2 \rangle.$$

Find the matrix representation of T with respect to the standard ordered basis

For \mathbb{R}^2 and \mathbb{R}^3 .

So if $V = \mathbb{R}^2$ and $W = \mathbb{R}^3$

$$v_1 = \langle 1, 0 \rangle \quad w_1 = \langle 1, 0, 0 \rangle$$

$$v_2 = \langle 0, 1 \rangle \quad w_2 = \langle 0, 1, 0 \rangle$$

$$w_3 = \langle 0, 0, 1 \rangle.$$

Thus $B = \{v_1, v_2\}$ and $C = \{w_1, w_2, w_3\}$.

$$T(v_1) = T(\langle 1, 0 \rangle) = \langle 1, 0, 3 \rangle = w_1 + 0w_2 + 3w_3$$

$$T(v_2) = T(\langle 0, 1 \rangle) = \langle -2, 0, 2 \rangle = -2w_1 + 0w_2 + 2w_3.$$

Hence we have:

$$[T]_B^C = [T(v_1) \quad T(v_2)] = \begin{bmatrix} 1 & -2 \\ 0 & 0 \\ 3 & 2 \end{bmatrix}.$$

If we change the order of the basis in $V = \mathbb{R}^2$ to $\{v_2, v_1\}$ and call this new ordered basis B' , then the matrix representation of T becomes:

$$[T]_{B'}^C = [T(v_2) \quad T(v_1)] = \begin{bmatrix} -2 & 1 \\ 0 & 0 \\ 2 & 3 \end{bmatrix}.$$

If we let B be the basis for $V = \mathbb{R}^2$ and let

$C' = \{u_1, u_2, u_3\} = \{\langle 0,0,1 \rangle, \langle 0,1,0 \rangle, \langle 1,0,0 \rangle\}$ then

$$T(v_1) = T(\langle 1,0 \rangle) = \langle 1,0,3 \rangle = 3u_1 + 0u_2 + u_3$$

$$T(v_2) = T(\langle 0,1 \rangle) = \langle -2,0,2 \rangle = 2u_1 + 0u_2 - 2u_3.$$

So we get:

$$[T]_{B'}^{C'} = [T(v_1) \quad T(v_2)] = \begin{bmatrix} 2 & 3 \\ 0 & 0 \\ -2 & 1 \end{bmatrix}.$$

Ex. Let $T: P_3(\mathbb{R}) \rightarrow P_2(\mathbb{R})$ be the linear transformation defined by

$T(p(x)) = p'(x) + p(0)$. Let B and C be the standard ordered bases for $P_3(\mathbb{R})$ and $P_2(\mathbb{R})$ respectively. Find the matrix representation of T .

The standard ordered basis for $P_3(\mathbb{R})$ is:

$$v_1 = 1, \quad v_2 = x, \quad v_3 = x^2, \quad v_4 = x^3.$$

The standard ordered basis for $P_2(\mathbb{R})$ is:

$$w_1 = 1, \quad w_2 = x, \quad w_3 = x^2.$$

$$T(v_1) = T(1) = 1 = 1(1) + 0(x) + 0(x^2)$$

$$T(v_2) = T(x) = 1 = 1(1) + 0(x) + 0(x^2)$$

$$T(v_3) = T(x^2) = 2x = 0(1) + 2(x) + 0(x^2)$$

$$T(v_4) = T(x^3) = 3x^2 = 0(1) + 0(x) + 3(x^2).$$

Thus we have:

$$[T]_B^C = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{bmatrix}.$$

Ex. Let $V = \mathbb{R}^2$ and $W = \mathbb{R}^2$, each with the standard ordered basis B . Suppose

$$T: V \rightarrow W \text{ by } T(\langle a_1, a_2 \rangle) = \langle 4a_1 + 6a_2, -4a_1 + 2a_2 \rangle.$$

a. Find the matrix representation of T .

b. Suppose V has the standard ordered basis but W has the ordered basis

$B' = \{w_1, w_2\} = \{\langle 1, 1 \rangle, \langle 3, -1 \rangle\}$. Find the matrix representation of T .

a. Since V and W both have the standard ordered basis we have:

$$\begin{aligned} v_1 &= \langle 1, 0 \rangle & w_1 &= \langle 1, 0 \rangle \\ v_2 &= \langle 0, 1 \rangle & w_2 &= \langle 0, 1 \rangle. \end{aligned}$$

$$T(v_1) = T(\langle 1, 0 \rangle) = \langle 4, -4 \rangle; \quad T(v_2) = T(\langle 0, 1 \rangle) = \langle 6, 2 \rangle.$$

$$[T]_B = \begin{bmatrix} 4 & 6 \\ -4 & 2 \end{bmatrix}.$$

b. $T(\langle 1, 0 \rangle) = \langle 4, -4 \rangle$ and $T(\langle 0, 1 \rangle) = \langle 6, 2 \rangle$ with respect to the standard ordered basis for both V and W . That is

$$\begin{aligned} \langle 4, -4 \rangle &= 4e_1 - 4e_2 = 4\langle 1, 0 \rangle - 4\langle 0, 1 \rangle \\ \langle 6, 2 \rangle &= 6e_1 + 2e_2 = 6\langle 1, 0 \rangle + 2\langle 0, 1 \rangle. \end{aligned}$$

Now we need to express $\langle 4, -4 \rangle$ and $\langle 6, 2 \rangle$ in terms of the new basis vectors $B' = \{w_1', w_2'\} = \{\langle 1, 1 \rangle, \langle 3, -1 \rangle\}$.

$$T(v_1) = \langle 4, -4 \rangle = a_1 w_1' + a_2 w_2' = a_1 \langle 1, 1 \rangle + a_2 \langle 3, -1 \rangle,$$

$$\text{so we need to solve } 4 = a_1 + 3a_2$$

$$-4 = a_1 - a_2.$$

Solving these simultaneous equations we get: $a_1 = -2$, $a_2 = 2$.

That is, we have:

$$T(v_1) = \langle 4, -4 \rangle = -2 \langle 1, 1 \rangle + 2 \langle 3, -1 \rangle = -2w_1' + 2w_2'.$$

Similarly,

$$T(v_2) = \langle 6, 2 \rangle = a_1 w_1' + a_2 w_2' = a_1 \langle 1, 1 \rangle + a_2 \langle 3, -1 \rangle,$$

$$\text{so we need to solve: } 6 = a_1 + 3a_2$$

$$2 = a_1 - a_2.$$

Solving these simultaneous equations we get: $a_1 = 3$, $a_2 = 1$.

That is, we have:

$$T(v_2) = \langle 6, 2 \rangle = 3 \langle 1, 1 \rangle + 1 \langle 3, -1 \rangle = 3w_1' + w_2'.$$

So with respect to the ordered bases $B = \{v_1, v_2\} = \{\langle 1, 0 \rangle, \langle 0, 1 \rangle\}$ for V and $B' = \{w_1', w_2'\} = \{\langle 1, 1 \rangle, \langle 3, -1 \rangle\}$ for W we have:

$$T(v_1) = \langle 4, -4 \rangle = -2 \langle 1, 1 \rangle + 2 \langle 3, -1 \rangle = -2w_1' + 2w_2'.$$

$$T(v_2) = \langle 6, 2 \rangle = 3 \langle 1, 1 \rangle + 1 \langle 3, -1 \rangle = 3w_1' + w_2'.$$

Thus T has the matrix representation:

$$[T]_{B'}^B = \begin{bmatrix} -2 & 3 \\ 2 & 1 \end{bmatrix}.$$

Ex. Again let $V = \mathbb{R}^2$ and $W = \mathbb{R}^2$ and $T: V \rightarrow W$ by

$$T(\langle a_1, a_2 \rangle) = \langle 4a_1 + 6a_2, -4a_1 + 2a_2 \rangle.$$

a. Find the matrix representation of T if V has the ordered basis

$$C = \{v_1', v_2'\} = \{\langle 2, 1 \rangle, \langle -1, 2 \rangle\} \text{ and } W \text{ has the standard ordered basis } B.$$

b. Find the matrix representation of T if V has the ordered basis

$$C = \{v_1', v_2'\} = \{\langle 2, 1 \rangle, \langle -1, 2 \rangle\} \text{ and } W \text{ has the ordered basis}$$

$$B' = \{w_1', w_2'\} = \{\langle 1, 1 \rangle, \langle 3, -1 \rangle\}.$$

a. So the ordered bases for V and W are given by:

$$v_1' = \langle 2, 1 \rangle$$

$$w_1 = \langle 1, 0 \rangle$$

$$v_2' = \langle -1, 2 \rangle$$

$$w_2 = \langle 0, 1 \rangle.$$

$$T(v_1') = T(\langle 2, 1 \rangle) = \langle 8 + 6, -8 + 2 \rangle = \langle 14, -6 \rangle = 14w_1 - 6w_2$$

$$T(v_2') = T(\langle -1, 2 \rangle) = \langle -4 + 12, 4 + 4 \rangle = \langle 8, 8 \rangle = 8w_1 + 8w_2.$$

So the matrix representation of T is

$$[T]_C^B = \begin{bmatrix} 14 & 8 \\ -6 & 8 \end{bmatrix}.$$

b. With respect to the **standard** ordered basis for W we have:

$$T(v_1') = T(\langle 2, 1 \rangle) = \langle 14, -6 \rangle$$

$$T(v_2') = T(\langle -1, 2 \rangle) = \langle 8, 8 \rangle.$$

So we have to express $\langle 14, -6 \rangle$ and $\langle 8, 8 \rangle$ with respect to the new ordered basis for W given by $B' = \{w_1', w_2'\} = \{\langle 1, 1 \rangle, \langle 3, -1 \rangle\}$.

$$\langle 14, -6 \rangle = aw_1' + bw_2' = a\langle 1, 1 \rangle + b\langle 3, -1 \rangle = \langle a + 3b, a - b \rangle$$

$$14 = a + 3b$$

$$\underline{-6 = a - b}$$

$$20 = 4b \implies b = 5, a = -1. \text{ So we have:}$$

$$T(v_1') = \langle 14, -6 \rangle = -\langle 1, 1 \rangle + 5\langle 3, -1 \rangle = -w_1' + 5w_2'.$$

$$\langle 8, 8 \rangle = aw_1' + bw_2' = a\langle 1, 1 \rangle + b\langle 3, -1 \rangle = \langle a + 3b, a - b \rangle$$

$$8 = a + 3b$$

$$\underline{8 = a - b}$$

$$0 = 4b \implies b = 0, a = 8. \text{ So we have:}$$

$$T(v_2') = \langle 8, 8 \rangle = 8\langle 1, 1 \rangle = 8w_1' + 0w_2'.$$

Thus the matrix representation of T is:

$$[T]_{C'}^{B'} = \begin{bmatrix} -1 & 8 \\ 5 & 0 \end{bmatrix}.$$

Ex. Define a linear transformation $T: M_{2 \times 2}(\mathbb{R}) \rightarrow P_2(\mathbb{R})$ with respect to the standard ordered basis $B = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$ for $M_{2 \times 2}(\mathbb{R})$ and $C = \{1, x, x^2\}$ for $P_2(\mathbb{R})$ by

$$T \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} \right) = (a + d) + (2c - b)x + (a + 2d)x^2. \quad \text{Find } [T]_B^C.$$

$$v_1 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \quad v_2 = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \quad v_3 = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \quad v_4 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

$$w_1 = 1, \quad w_2 = x, \quad w_3 = x^2.$$

$$T(v_1) = T \left(\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \right) = 1 + x^2 = w_1 + w_3; \quad T(v_1) = \langle 1, 0, 1 \rangle_C$$

$$T(v_2) = T \left(\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \right) = -x = -w_2; \quad T(v_2) = \langle 0, -1, 0 \rangle_C$$

$$T(v_3) = T \left(\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \right) = 2x = 2w_2; \quad T(v_3) = \langle 0, 2, 0 \rangle_C$$

$$T(v_4) = T \left(\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right) = 1 + 3x^2 = w_1 + 3w_3; \quad T(v_4) = \langle 1, 0, 3 \rangle_C$$

$$\begin{aligned} [T]_B^C &= [T(v_1) \quad T(v_2) \quad T(v_3) \quad T(v_4)] \\ &= \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & -1 & 2 & 0 \\ 1 & 0 & 0 & 3 \end{bmatrix}. \end{aligned}$$

Def. Let $T, U: V \rightarrow W$ be arbitrary functions, where V and W are vector spaces. Define $(\mathbf{T} + \mathbf{U}): V \rightarrow W$ by $(\mathbf{T} + \mathbf{U})(v) = T(v) + U(v)$ for all $v \in V$ and

$$(\alpha\mathbf{T}): V \rightarrow W \text{ by } (\alpha\mathbf{T})(v) = \alpha T(v) \text{ for all } v \in V.$$

Theorem: Let V and W be vector spaces and $T, U: V \rightarrow W$ be linear.

- a. For all $\alpha \in \mathbb{R}$, $\alpha T + U$ is linear.
- b. The collection of all linear transformations from V to W is a vector space.

Proof: a. Let $u, v \in V$ and $c \in \mathbb{R}$. Then

$$\begin{aligned} (\alpha T + U)(cu + v) &= \alpha T(cu + v) + U(cu + v) \\ &= \alpha[cT(u) + T(v)] + cU(u) + U(v) \\ &= c[\alpha T(u) + U(u)] + \alpha T(v) + U(v) \\ &= c(\alpha T + U)(u) + (\alpha T + U)(v). \end{aligned}$$

So $\alpha T + U$ is linear.

b. Notice that $T_0(v) = 0$ is the zero vector in the collection of linear transformations from V to W .

By part a, this collection is closed under addition and scalar multiplication.

It's straight forward to verify that the vector space axioms hold.

Def. Let V and W be vector spaces. We denote the vector space of all linear transformations from V to W by $\mathcal{L}(V, W)$. If $W = V$ then we write $\mathcal{L}(V)$.

Theorem: Let V and W be finite dimensional vector spaces with ordered bases B and C . Let $T, U: V \rightarrow W$ be a linear transformation. Then

a. $[T + U]_B^C = [T]_B^C + [U]_B^C$

b. $[\alpha T]_B^C = \alpha [T]_B^C$ for all $\alpha \in \mathbb{R}$.

Proof: a. Let $B = \{v_1, \dots, v_n\}$ and $C = \{w_1, \dots, w_m\}$ be ordered bases for V and W respectively. For $1 \leq j \leq n$:

$$T(v_j) = a_{1j}w_1 + a_{2j}w_2 + \dots + a_{mj}w_m$$

$$U(v_j) = b_{1j}w_1 + b_{2j}w_2 + \dots + b_{mj}w_m.$$

Hence:

$$(T + U)(v_j) = (a_{1j} + b_{1j})w_1 + (a_{2j} + b_{2j})w_2 + \dots + (a_{mj} + b_{mj})w_m$$

and $([T + U]_B^C)_{ij} = a_{ij} + b_{ij} = ([T]_B^C)_{ij} + ([U]_B^C)_{ij}.$

b. follows in similar fashion.

Ex. Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ and $U: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ be linear transformations defined by

$$T(\langle a_1, a_2 \rangle) = \langle 2a_1 - a_2, a_2, a_2 - 3a_1 \rangle \quad \text{and}$$

$$U(\langle a_1, a_2 \rangle) = \langle a_1 + a_2, 2a_2, 3a_1 - 2a_2 \rangle.$$

Let B and C be the standard ordered bases for \mathbb{R}^2 and \mathbb{R}^3 respectively. Then

$$T(v_1) = T(\langle 1, 0 \rangle) = \langle 2, 0, -3 \rangle; \quad U(v_1) = U(\langle 1, 0 \rangle) = \langle 1, 0, 3 \rangle$$

$$T(v_2) = T(\langle 0, 1 \rangle) = \langle -1, 1, 1 \rangle; \quad U(v_2) = U(\langle 0, 1 \rangle) = \langle 1, 2, -2 \rangle$$

$$[T]_B^C = \begin{bmatrix} 2 & -1 \\ 0 & 1 \\ -3 & 1 \end{bmatrix} \quad [U]_B^C = \begin{bmatrix} 1 & 1 \\ 0 & 2 \\ 3 & -2 \end{bmatrix}.$$

Notice that $(T + U)(\langle a_1, a_2 \rangle) = \langle 3a_1, 3a_2, -a_2 \rangle$

$$\Rightarrow [T + U]_B^C = \begin{bmatrix} 3 & 0 \\ 0 & 3 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 2 & -1 \\ 0 & 1 \\ -3 & 1 \end{bmatrix} + \begin{bmatrix} 1 & 1 \\ 0 & 2 \\ 3 & -2 \end{bmatrix} = [T]_B^C + [U]_B^C.$$